Aspects of Dynamical Simulations, Emphasizing Nosé and Nosé-Hoover Dynamics and the Compressible Baker Map

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Abstract: Aspects of the Nosé and Nosé-Hoover dynamics developed in 1983–1984 along with Dettmann’s closely related dynamics of 1996, are considered. We emphasize paradoxes associated with Liouville’s Theorem. Our account is pedagogical, focused on the harmonic oscillator for simplicity, though exactly the same ideas can be, and have been, applied to many-body systems. Nosé, Nosé-Hoover, and Dettmann flows were all developed in order to access Gibbs’ canonical ensemble directly from molecular dynamics. Unlike Monte Carlo algorithms dynamical flow models are often not ergodic and so can fail to reproduce Gibbs’ ensembles. Accordingly we include a discussion of ergodicity, the visiting of all relevant microstates corresponding to the desired ensemble. We consider Lyapunov instability too, the usual mechanism for phase-space mixing. We show that thermostated harmonic oscillator dynamics can be simultaneously expanding, incompressible, or contracting, depending upon the chosen “phase space”. The fractal nature of nonequilibrium flows is also illustrated for two simple two-dimensional models, the hard-disk-based Galton Board and the time-reversible Baker Map. The simultaneous treatment of flows as one-dimensional and many-dimensional suggests some interesting topological problems for future investigations.

Key words: Nosé oscillator, Nosé-Hoover oscillator, Dettmann oscillator, nonlinear dynamics, Galton Board, Baker Map

I. INTRODUCTION: A SUMMARY OF DYNAMICAL MILESTONES

Gibbs’ formulation of statistical mechanics uses averages over all of phase space as predictors of equilibrium behavior. Metropolis, the Rosenbluths, and the Tellers implemented Gibbs’ program with their “Monte Carlo” algorithm [1]. They emphasized that their algorithm is ergodic, capable of covering all of phase space, and applied it successfully to the equation of state of hard disks. Gibbs showed that phase-space averages over “all states” could be used to calculate properties of systems at constant energy, or, by weighting the states differently, at constant temperature or pressure or both. Some 50 years later, computers made it possible to compute such averages numerically, at first for very small systems. This was accomplished by moving particles with probabilities corresponding to the intended ensemble [1]. We provide two educational examples of Monte Carlo simulation in Section II.

Berni Alder and Tom Wainwright developed “Molecular Dynamics” shortly thereafter [2]. The two methods agreed well for fixed-energy hard-sphere systems at equilibrium. Fixed-temperature Monte Carlo simulation is limited to equilibrium problems. Equilibrium Monte Carlo simulations had no precise dynamical analog until Nosé’s innovative work of 1984 [3–6]. “Nonequilibrium Molecular Dynamics”, which could deal with flows of momentum and energy, had been developed in the 1970s [7]. The velocities, kinetic temperatures, and heat fluxes could all be controlled by brute-force adjusting and rescaling. The resulting fixed
moments of the distribution turned out to promote viscous and thermal flows in line with hydrodynamic expectations in relatively small systems, with only a few or at most a few hundred interacting particles. We describe some equilibrium example flows in Section III. It was discovered that the brute-force rescaling was equivalent to linear feedback control of the momenta in the differential equations governing particle motion. We illustrate this equivalence in Section IV and introduce the Galton Board problem as the prototype example.

In 1984 Shuichi Nosé formulated a particle mechanics consistent with Gibbs’ canonical ensemble. His work was grounded in Hamiltonian mechanics but with a novel addition designed to promote energy mixing. Nosé’s mechanism for mixing states of different energies was an external “time-scaling” variable \( s \). A dozen years later Dettmann discovered that \( s \) can be best be interpreted as the phase-space probability density, \( s = f(q,p,\zeta) \), where the “friction coefficient” \( \zeta \) in Nosé’s work is the momentum conjugate to \( s, \rho_s = \zeta \). This same notion was independently discovered three years later by Bond, Leimkuhler, and Laird [8]. Their work attracted Nosé’s interest more strongly than had Dettmann’s [7, 9, 10], which Bill had discussed with Nosé in 1996. Nosé’s 1984 work and Dettmann’s 1996 achievement are detailed in Section V.

Meeting Nosé in Paris in 1984 Bill Hoover developed a flow-based model, like Liouville’s Theorem for incompressible Hamiltonian flows, but applying to compressible flows of just the kind invented by Nosé. Hoover emphasized the usefulness of the harmonic oscillator in understanding Nosé’s approach [5]. The simplicity of that model led to its independent rediscovery by Sprott a decade later [11, 12]. We adopt that same model here as our primary pedagogical tool. The simplest possible thermostating mechanism, linear feedback, gave rise to a Gaussian distribution for the friction coefficient \( \zeta = \rho_s \), as is described in Section V.

Thermostating from a more general viewpoint, using higher moments, was glimpsed by Hoover in 1985 [13], and treated comprehensively in a pair of important papers [14] by Bauer, Bulgac, and Kusnezov in the early 90s. The 2015 (Ian) Snook Prize problem led Tapias, Bravetti, and Sanders [15] to a “Logistic” thermostat with an arctangent switch between the heating and cooling functions of their external frictional control variable. Their work was soon elaborated by Sprott [16], who considered on-off “bang-bang” control of temperature and showed numerically that the resulting control variable has a singular exponential distribution in this limit rather than the Gaussian distribution resulting from Nosé’s integral control. These ideas are also illustrated in Section V.

In Section VI we illustrate and discuss a paradox involving three descriptions of the Nosé-Hoover oscillator flow. These suggest (wrongly, of course) that the same flow can be simultaneously expanding, contracting, or incompressible, depending upon the coordinates used to describe the flow.

Section VII provides our views on numerical methods, developed over 40 years, and influenced particularly by our colleague Clint Sprott [17], whose imaginative use of color has provided a powerful adjunct to the understanding of nonequilibrium flows. Because bifurcation and chaos is necessary to any statistical view of dynamical systems we include the characterization of flows in terms of their Lyapunov spectra in this Section.

Sections VIII and IX deal with our general conclusions concerning the simulation of nonequilibrium steady states, the formation of fractal repellors and attractors and the association of the macroscopic Second Law of Thermodynamics with microscopic thermostated models.

Our final Section X is a bit speculative, as must be any view of the future, and suggests that the fractal geometry of nonlinear chaotic flows still holds more interesting lessons for us. We stress the difference between the continuous, paradoxical, and contentious view of mathematics and the discrete grid-based approach of computational statistical mechanics.

II. MONTE CARLO AS DEVELOPED IN THE 1950s

As computer hardware improved in the American National Laboratories, predominantly at Los Alamos and Livermore, the applications became scientifically interesting. In the decade following the Second World War both Enrico Fermi and Edward Teller became interested in developing computer applications to problems with statistical mechanical roots. For the first time manybody problems and problems involving billions of operations became tractable. The Monte Carlo technique [1] was developed at the Los Alamos laboratory, with equation of state results calculated in the early 1950s followed soon after by dynamical studies of one-dimensional anharmonic chains, the “Fermi-Pasta-Ulam problem”, by 1953 [18]. That innovative work was soon followed by Alder and Wainwright’s dynamical studies of hard disks and spheres [19] complemented by Wood and Jacobsen’s Monte Carlo simulations of these same systems [20]. Let us next look at two illustrative examples of the Monte Carlo simulation technique with two simple systems, the harmonic oscillator and its quartic-oscillator relative.

II. 1. Monte Carlo Evaluation of Canonical Harmonic Oscillator Moments

As a warmup demonstration problem let us apply the Monte Carlo method to a test problem with well-known dynamical and ensemble-averaged answers, the one-dimensional harmonic oscillator. As usual we choose the mass, force constant, temperature, and Boltzmann’s constant all equal to unity. Gibbs’ canonical phase-space distribution for the oscillator coordinate-momentum \((q,p)\) pair, is the simple Gaussian: \(f(q,p) = e^{-(q^2+p^2)/2}/(2\pi)\). The resulting
mean values of the even moments of $q$ and $p$ are products of the odd integers:

$$
\{q^2, p^2, q^4, p^4, q^6, p^6, q^8, p^8, \ldots \} = \{1, 1, 3, 3, 15, 15, 105, 105, \ldots \}
$$

Metropolis’ group published the method in 1953 [1] – (and there is some controversy as to the relative contributions of the five researchers) [18]. They pointed out that a detailed balance between two states of energy $E_i, E_j$ with relative probabilities obeying Gibbs’ canonical (exponential) distribution, $f_i/f_j = e^{-E_i+E_j}$, can be achieved by an imaginary equilibrium dynamics, a “Monte Carlo simulation”, in which changes of state occur at a definite rate. Consider just one equilibrium dynamics, a “Monte Carlo simulation”, in which the states, a stationary state results. This state has the desired distribution, $f$, the Gibbs’ canonical ratio,

$$
f = e^{-E_i+E_j},
$$

where $E_i$ and $E_j$ are the energies of the two states. If the transition rate from the lower state (say the $i$th state) is less than that from the higher state by a factor $e^{E_j−E_i}$, just offsetting the relative probabilities of the states, a stationary state results. This state has the desired canonical ratio, $f_i/f_j = e^{-E_i+E_j}$. If this can be achieved for all pairs of states, and all such pairs are accessible, then Gibbs’ canonical ensemble can be realized numerically, as a limiting case. As the number of states is astronomical, for even a one-body system, it is necessary to understand the convergence rate of Monte Carlo simulations. Let us pursue the oscillator problem with its known canonical distribution of the coordinate, $e^{-q^2/2}/\sqrt{2\pi}$.

A Monte Carlo program implementing this idea for the oscillator coordinate causes a single test oscillator to make random jumps within a spatial interval $−J < dq <+J$. The jump $dq$ occurs with probability 1 if the energy drops and with a lesser probability $e^{−dE}$ if it rises. The uphill jump with probability $e^{−dE}$ is implemented by choosing an additional random number $0 < R < 1$ and accepting the move when $R$ is sufficiently small, $R < e^{−dE}$. This single-particle oscillator program needs two random numbers when the new energy is higher – one for the jump and one for the acceptance test. Only one random number is needed (for the jump alone) when the energy is lower. The heart of the program can be summarized by a single line of pseudocode:

```plaintext
if( (Enew.lt.Eold).or. (rund(intx,enty).lt.dexp(-Enew+Eold)) ) qold = qnew
```

We wrote such a billion-jump program using the following simple generator `rund(intx,enty)`, where the two arguments are the “seeds” of the random number `rund`. As the routine is called the corresponding sequence of `intx` and `enty` values goes through all 4,194,304 combinations $0 \leq (\text{intx,enty}) \leq 2047$. We began with $(\text{intx,enty})$ both zero. These seeds change each time a new number is generated. Here is `rund`:

```plaintext
intx = mod(i,2048)
j = j + (i - intx)/2048
inty = mod(j,2048)
rund = (intx + 2048*inty)/4194304.d00
```

This choice reproduces the second and fourth moments $\langle q^2, q^4 \rangle$ within 0.01 for maximum jump lengths $J$ of 1, 2, or 4, where $[−J < dq <+J]$. The mean squared jump length $\langle dq^2 \rangle$ was 0.61 for $J = 2$, 0.87 for $J = 4$, and 0.53 for $J = 8$, suggesting that the relatively large jump-length interval with $J = 4$ is best from the standpoint of phase-space exploration.

A longer run of one billion Monte Carlo steps with $J = 1/2$ revealed an interesting oscillation in the fourth moment, $\langle q^4 \rangle$, with a periodic duration of roughly 30 million steps. The long-time mean value of that fourth moment appears to be converging in the neighborhood of 2.983 rather than exactly 3. The relatively short period and the half-percent error in the moment suggest that the `rund` generator is not well suited to this type of Monte Carlo simulation.

The built-in gfortran generator, `rand(intx)` is arguably better, but still far from perfect. With `rand` a ten-billion step run reveals a period on the order of one billion steps converging in the neighborhood of $\langle q^4 \rangle = 2.9984$. A similar run, but discarding the first $10^8$ random numbers, leads to a similar period with apparent convergence to 2.9985. Finally, a program using `pairs` of random numbers for each step (an effort to enhance and better characterize periodicity) gave apparent convergence to 3.00007, again with oscillation periods of about one billion steps. A careful look revealed that the sequence of random numbers produced by `rand` repeats precisely after 715,827,882 calls and evidently creates a resonant periodicity, with that same frequency, in the oscillator itself.

This same strategy, accepting moves raising the potential energy with relative probability $e^{−dE}$ has been successfully applied to manybody problems ever since Metropolis’ work. Such Monte Carlo sampling is not extendable to “nonequilibrium” simulations (those with specified velocity or temperature gradients for example) while Nosé’s method is [21].

By simulating random jumps in phase space the Monte Carlo approach automatically accesses configurations over a wide range of potential energies.

This harmonic oscillator example teaches an important lesson: test random number implementations with a few simple applications having known answers prior to embarking on a “new” type of simulation. In Section VIII we will use “Random_Number(r)”, a better FORTRAN random number generator, in another Monte Carlo application.

### II. 2. Monte Carlo Construction of Quartic Oscillator Ensembles

Another application of the Monte Carlo method is the construction of small-system Gibbs’ ensembles for given values of the energy or temperature. Although dynamical
techniques able to generate such an ensemble from a single
trajectory were a long time in coming, the statistical mechan-
ics of ensembles is an excellent fit with Monte Carlo tech-
niques. Let us illustrate this idea for the example of a quartic
oscillator, with the Hamiltonian \( \mathcal{H}_4 = \frac{q^4}{4} + \frac{p^2}{2} \).

Fig. 1 shows two versions of quartic-oscillator Monte
Carlo ensembles. In the first \((q,p)\) pairs come from the ran-
dom number generator \( \text{rund}(\text{int}x, \text{int}y) \), with energies
up to \( \frac{q^4}{4} + \frac{p^2}{2} = 5 \), selected from within the ran-
domly accessed rectangle:

\[
-\sqrt{20} < q < +\sqrt{20} ; -\sqrt{10} < p < +\sqrt{10}.
\]

Enlargement shows several line segments in the microcanon-
cal distribution at top left, indicating correlation, greatly re-
duced by discarding every third random number. The canoni-
cal distribution at the right, with the same number of ac-
cepted points (10,000) was generated by accepting random
choices in a larger rectangle, \(-10 < (q,p) < +10\) with proba-
bility \( e^{-(q^4/4+p^2/2)} \) by accepting \((q,p)\) whenever \( R < e^{-(q^4/4+p^2/2)} \). This example, like the harmonic moments
simulation, is interesting in that both of them point out short-
comings of \( \text{rund}(\text{int}x, \text{int}y) \). Though the correlations
are too small to see here at the scale of the microcanon-
cal case, they are quite obvious in the canonical ensemble
sample at the upper right. For most purposes this same
\( \text{rund}(\text{int}x, \text{int}y) \) generator is perfectly adequate.

Fig. 1. The random number generator \( \text{rund} \) used to generate the ersatz microcanonical (at the left) and canonical (at the right) dis-
btributions shows serial correlation in both cases. The flaws can be
seen easily in an enlarged view of this figure. Discarding every third
of the random numbers improves the situation, as can be seen in the
canonical results to the right. Each plot contains 10,000 points

\[ \text{III. MOLECULAR DYNAMICS FROM THE 1950s} \]

Gibbs’ statistical mechanics is equilibrium-based. Its simplest “microcanonical ensemble” formulation de-
scribes many similar microscopic \( \{q,p\} \) copies (the “ensemble’’) of a fixed mass of fluid confined to a periodic volume
\( V \) with a fixed energy \( E \). In the various copies the pressure
and temperature fluctuate, with their instantaneous values
defined through the virial theorem and the ideal-gas ther-

The coordinate, velocity, and acceleration are respectively
\((q,v,a)\). Though the velocity appears in the underlying
“leapfrog derivation” the coordinates can be calculated as
centered second differences without any need to calculate or
store the half-step velocities.

For the harmonic oscillator the acceleration is \(-q(t)\) and
the analytic solution of the finite-difference algorithm is pe-
riodic in time, but with a slightly higher oscillation frequency
deviating quadratically from the exact oscillator trajectory,
\( q = \cos(t) \):

\[
q = \cos(\omega t) ; \omega dt = \cos^{-1}[1 - (dt^2/2)]
\]

[Leapfrog Algorithm Solution].

By a simple “rescaling of the time”, a concept to which
we return in Section V, this approximate algorithm can be
made exact for the oscillator. Fermi, Pasta, and Ulam used
the leapfrog algorithm to study the dynamical properties of
anharmonic chains. They were mightily surprised that the
chains showed no simple approach to equilibrium.

Soon after, Berri Alder and Tom Wainwright, helped
by Mary Ann Mansigh (now Karlsen) [22], at the Liver-
more Laboratory in California, began to study the “event-driven” molecular dynamics of hard disks and spheres [2]. They computed the times to each pair of particles’ next collision accurately. The resulting geometry, coupled with conservation of momentum and energy, gives the post-collision velocities of the two colliding particles. The simulation then continues to the next collision.

Unlike Fermi’s nonlinear chains, hard-particle systems soon came to thermal equilibrium, nicely reproducing the Maxwell-Boltzmann velocity distribution $f(v) \propto e^{-mv^2/2kT}$. The most surprising finding of theLivermore work was that (two-dimensional) hard disks underwent a fluid-solid phase transformation at a density near three-fourths of the closest-packed “triangular-lattice” structure. The details of the transition have been progressively refined, as recently as 2013, and are now quite well known [23]. Paradoxically the transition in three dimensions, with hard spheres freezing at two-thirds the close-packed density, had already been characterized fairly well, by both molecular dynamics and Monte Carlo, in the 1950s [19, 20]. The three-dimensional transition is both broader and sharper than is its two-dimensional little brother.

**IV. ISOKINETIC NONEQUILIBRIUM DYNAMICS FROM THE 1970s**

Fig. 2. To the left we show the definition of $(\alpha, \beta)$ which define the location and exit velocity of each Galton-Board collision. To the right we see the fractal attractor distributions that result with gravitational field strengths of $E = 1, 2, 3,$ and 4. This work is fully described in Ref. [24].

Molecular dynamics, when equipped with boundary conditions allowing heat transfer, can describe dissipative stationary states requiring work for their maintenance and discharging an equivalent time-averaged amount of heat to their environment. Nonequilibrium molecular dynamics simulations with boundary velocities and temperatures were first performed in the 1970s, [13, 21] by controlling particle velocities with “thermostat forces”. Implementing this idea required a definition of “temperature”, for which the ideal-gas definition, $mkT \equiv \langle p^2 \rangle$ was readily adopted. Gibbs’ statistical mechanics had backed this definition with the observation that at equilibrium, so long as the potential energy $\Phi(q)$ was independent of the kinetic, $K = \sum mv^2/2 = NDKT/2$. Here $D$ is the dimensionality and $ND$ is the number of Cartesian degrees of freedom in the sum. Gibbs’ statistical mechanics shows that exactly the same velocity distribution applies to dense matter as to the ideal gas. These same thermostat forces can also be generalized to simulating the mix of energy states required for Gibbs’ canonical weighting of energies, $e^{-E/kT}$.

The Department of Applied Science of the University of California at Davis was founded in 1963 in response to Edward Teller’s wish for a wider dissemination of the research opportunities at the Lawrence Radiation Laboratory. By 1970 Berni Alder had helped Bill Hoover to a Professorship there. Bill soon found a willing student, Bill Ashurst, from the Sandia Laboratory across the street [East Avenue], to work with him on nonequilibrium simulation techniques. Ashurst’s PhD project, Dense Fluid Shear Viscosity and Thermal Conductivity via Nonequilibrium Molecular Dynamics, was carried out between January 1972 and May 1974. Ashurst developed computational “fluid walls”, chambers containing a fixed number of particles, with reflecting boundaries. At the end of each Leapfrog timestep the first and second velocity moments in the fluid walls were adjusted to conform to the specified mean velocity and temperature: $\{v \rightarrow v + \alpha + \beta v\}$.

Bill’s demonstration problems included dozens of simulations of viscous flows for dense fluids confined between two oppositely-moving fluid walls. Offsetting the work done and the heat transferred by the elastic wall collisions and the continuous momentum flow between wall and system particles, Ashurst maintained nonequilibrium steady states by alternating leapfrog steps with fluid-wall velocity adjustments on the order of a percent, maintaining the boundary velocities and temperatures. In this two-step process work was performed, and heat extracted, in such a way as to obey a time-averaged version of the Second Law.

Perhaps the simplest example problem constrains a manybody system to a fixed kinetic temperature. To do this, using a frictional force, $-\zeta p$, the constraint of fixed kinetic energy has the form:

$$\{\dot{p} = F - \zeta p\} ;$$

$$\sum_1^N p \cdot \dot{p} = 0 = \sum_1^N [F - \zeta p] \cdot p \rightarrow \zeta = \sum_1^N F \cdot p / \sum_1^N p \cdot p .$$

The thermostat forces $\{-\zeta p\}$ exactly offset the natural fluctuations in the kinetic energy, forcing it to remain constant, providing isothermal (and isokinetic) fluid walls.

It is interesting to see that the friction coefficient $\zeta$, being proportional to the momenta, is time-reversible so that a reversed trajectory, with all of the $\{p\}$ together with the two wall values of $\{\zeta\}$ changing signs, satisfies exactly the same motion equations as did the forward trajectory. This time-symmetry is paradoxical (Loschmidt’s Paradox) because any irreversible process, viewed backward in time, makes no sense.
The physical explanation of the paradox was clarified in 1987 [24, 25]. Bill, Harald Posch, Brad Holian, and another PhD student of Bill’s, Bill Moran, discovered that time-reversible thermostat forces obeying the Second Law of Thermodynamics provide a dynamics which collapses onto a fractal (fractional dimensional!) attractor. These attractors are made up of a negligible fraction of all the Gibbs’ states present at equilibrium, but are still Lyapunov unstable, with tiny changes in the conditions leading to exponentially growing differences in the future. The reversed trajectory, likewise containing its own negligible portion of phase space (the “repellor”, with reversed velocities) is much less stable than the attractor. The reversed trajectory is invariably less stable than the attractor and cannot be generated directly from the dynamical equations. The only way to obtain the reversed trajectory is previously to compute, store, and reverse a forward trajectory.

One of the 1987 Toy Models [24], the “Galton Board”, demonstrated this explanation of the Second Law in terms of isokinetic dynamics. A particle falling through a regular lattice of fixed scatterers, in the presence of a gravitational field, was constrained to move at constant speed by imposing an isokinetic constraint on its motion. See Fig. 2. The locations of successive collisions with scatterers could be described by two angles. The angle $\alpha$ gives the location of the collision relative to the scatterer and the angle $\beta$ describes the outgoing velocity direction after that collision. For hard-disk scatterers the equilibrium distribution of the angles is perfectly uniform in a simple rectangle, with $0 < \alpha < \pi$ and $-1 < \sin(\beta) < +1$. The figure shows the definitions of the two angles to the left and the distributions of collisions that follow from four gravitational field strengths. The fractal attractor dimension occupied by the collisional states decreases with increasing field strength. Careful investigation shows that the dimension is always fractional so that the fraction of states in the steady state is negligible, just as the measures of a line in two-dimensional space or a surface in three dimensions have zero measure.

Ashurst’s heat-flow simulations were carried out by maintaining two fluid walls at different isokinetic temperatures. The resulting heat conductivities agreed fairly well with experimental data for liquid argon and were used in simulating stationary shockwaves. At Los Alamos this was accomplished by shrinking the volume as a function of time. At Livermore steady input and output flows far from the wave’s center were used to generate stationary shockwaves [26].

V. THE INFLUENCE OF NOSE’S 1984 TIME-SCALING DYNAMICS

Realistic computer simulations of dense fluid flows, even shockwaves [26], caused the continuing explosion of interest and participation in molecular dynamics we enjoy today. With the background of the isokinetic and isoenergetic nonequilibrium simulations of the 1970s many gifted researchers turned their attention to improving the state of the art. Among them Shuichi Nosé was particularly innovative. By an imaginative extension of Hamiltonian mechanics he invented a method for mixing energy states dynamically in such a way as to reproduce Gibbs’ canonical ensemble. This linking of computer simulations to well-established fundamental physics helped popularize simulations and led to the recognition of Berni Alder’s pioneering influence with his award of the National Medal of Science in 2009. Berni’s award was followed four years later with the Nobel Prizes in Chemistry for Martin Karplus, Michael Levitt, and Arieh Warshel. They developed realistic biological simulations using thermostated molecular dynamics with judicious quantum-mechanical additions.

The isothermal mechanics invented by Shuichi Nosé in 1983–1984 [3, 4] was a catalyst for this development. His seminal work was greatly extended in 1984–1996 [5–7, 9]. We introduce and discuss it here from a pedagogical point of view. Replicating Gibbs’ canonical ensemble with a deterministic Hamiltonian dynamics was Nosé’s goal. Two problems needed to be solved to accomplish it: (1) the new mechanics needed to access the energy states given by Gibbs’ canonical probability density, $f(q,p) \propto e^{-E/kT}$; (2) the new mechanics’ phase-space trajectory needed to speed up at higher energies and slow down at lower ones in just such a way as to convert the constant density microcanonical distribution to the exponential density canonical one. Nosé adopted Hamiltonian mechanics as his starting point. With the imaginative addition of “time scaling” he could vary the speed of phase-space travel (and more fundamentally the strain-rate of the corresponding compressible flow) to replicate Gibbs’ distribution.

Nosé’s highly original approach involves first the scaling of all the Hamiltonian momenta by a multiplicative time-scaling factor $(1/s) = e^{+E/kT + \zeta^2 \tau^2/2}$, where $\zeta = \eta \tau$ is a friction coefficient as well as the Hamiltonian momentum conjugate to $s$, and where $\tau$ governs the strength of the thermostating forces $\{-\zeta \tau^2 p\}$. Next, and finally, Nosé’s fundamental invention, the time-scaling factor $s$, must adjust the frequency of appearance of phase-space states in direct proportion to $e^{-E/kT} \propto f(q,p)$, Gibbs’ phase-space probability density.

Shortly after meeting with Nosé to discuss his work Hoover showed that frictional forces, $\{-\zeta p\}$, where $\zeta$ is determined by time-reversible feedback, $\zeta \propto \sum(p^2 - mkT)$, reproduce the results of Nosé’s isothermal mechanics directly from the phase-space continuity equation [5].

At Philippe Choquard’s Lausanne laboratory Hoover applied Nosé’s ideas to numerical simulations of a thermostated one-dimensional harmonic oscillator. This numerical work showed that the Nosé oscillator was far from ergodic. Instead, it generated a remarkable variety of toroidal solutions as well as a relatively-small chaotic sea [6].
The union of all these separate solutions was the three-dimensional Gaussian:
\[ f(q,p,ζ) = e^{-\mathcal{H}/kT} e^{-q^2/2} e^{-p^2/2} e^{-ζ^2/2} \]
[Nosé-Hoover].

A generation later Clint Sprott and the Hoovers showed that the oscillator model had toroidal orbits that formed interlocking rings [27]. More recently Lei Wang and Xiao-Song Yang found Nosé-Hoover oscillator trajectories in the form of knots, very far from the simple ellipses of the isokinetic model [28]. Here and in what follows, we forgo those fascinating topological surprises, mercilessly simplifying Nosé’s approach and its many possible generalizations, as formalized by Bauer, Bulgar, and Kusnezov [14]. Instead we choose to focus on the canonical oscillator problem with linear friction and with all of the various parameters in the model, including \( kT \), equal to unity.


The oscillator-based discovery that Nosé’s mechanics wasn’t necessarily ergodic opened up a new research area which is still quite active – finding motion equations which generate the entire canonical phase space distribution regardless of initial conditions. The most useful work along those lines, with many worked-out example problems, was pioneered by Bauer, Bulgar, and Kusnezov in two long and comprehensive readable papers in the Annals of Physics [14]. Their work generalized Hoover’s [13], showing that several thermostat variables, called “Demons” in Ref. [14], can be used simultaneously, with three Demons enough to simulate one-particle Brownian motion! Generally they found that additional nonlinearity enhances ergodicity. Fig. 3 compares Poincaré sections at the plane \( p = 0 \) for three varieties of thermostated oscillator including the far from ergodic Nosé-Hoover example:

\[ \{ \dot{q} = p; \dot{p} = -q - ζp; \dot{ζ} = p^2 - 1 \} \rightarrow f = e^{-q^2/2 - p^2/2 - ζ^2/2} \]
[Nosé-Hoover]

\[ \{ \dot{q} = p; \dot{p} = -q - ζ^3p; \dot{ζ} = p^2 - 1 \} \rightarrow f = e^{-q^2/2 - p^2/2 - ζ^4/4} \]
[Cubic ζ]

\[ \{ \dot{q} = p; \dot{p} = -q - ζ^3p; \dot{ζ} = p^4 - 3p^2 \} \rightarrow f = e^{-q^2/2 - p^2/2 - ζ^2/2} \]
[Cubic p].

Before long, in 1996, Hoover and Holian found [29] that the simplest combination of two moment-based Demons was enough to render the one-dimensional harmonic oscillator ergodic:

\[ \{ \dot{q} = p; \dot{p} = -q - ζp - ξp^3; \dot{ζ} = p^2 - 1 ; \dot{ξ} = p^4 - 3p^2 \} \]
[Hoover-Holian Ergodic].

This set of equations provides an entire four-dimensional Gaussian distribution for any initial condition [29]:

\[ f = e^{-q^2/2 - p^2/2 - ζ^2/2} \]
[Hoover-Holian].

In all of these cases the stationary distribution follows from the phase-space continuity equation, which is a generalization of the ideas used to derive Liouville’s Theorem:

\[ \frac{∂f}{∂t} = -\frac{∂f}{∂q} (\frac{∂q}{∂ζ}) + (\frac{∂f}{∂p}) + (\frac{∂f}{∂ζ}) + \frac{∂f}{∂p} \frac{∂p}{∂ζ} - \frac{∂f}{∂ζ} \frac{∂ζ}{∂ζ}. \]

Although only the last of these approaches is ergodic recent developments have shown that a single thermostat variable can provide ergodicity. A particularly interesting singular example was highlighted by Sprott [16] as an extension of the prize-winning work of Tapias, Bravetti, and Sanders, who used a hyperbolic tangent function of \( ζ \) to shift from heating (negative \( ζ \)) to cooling (with positive \( ζ \)) [15]:

\[ \{ \dot{q} = p; \dot{p} = -q + αp; \dot{ζ} = p^2 - 1 \} \]
[Sprott’ Signum Thermostat].

Here the minus sign is used for positive \( ζ \) and the plus sign for negative \( ζ \). The momentum \( p \) varies continuously in time, but with an occasional discontinuity in its first derivative. Sprott observed ergodicity for this model provided that the parameter \( α \) is chosen at least equal to the “Golden Ratio”, \( 1.618034 = \sqrt{5}/4 + (1/2) \). The details of this work are not yet understood. Fig. 4 illustrates the uniform coverage of the Poincaré section \( ζ = 0 \) obtained with Sprott’s Thermostat.

V. 2. Dettmann’s 1996 Contribution

to an Understanding of Nosé’s Approach

Bill and Carl Dettmann discussed the difficulty of rationalizing Nosé’s time-scaling step at a CECAM meeting one July evening in Lyon [7, 9]. By the next morning Dettmann had discovered that the simple step of multiplying Nosé’s Hamiltonian \( \mathcal{H}_N \) by \( s \), the mysterious time-scaling variable,
Gibbs’ three-dimensional Gaussian distribution can be con-
duced to understand the relatively complex relationship between
the speed of phase-space travel and probability density. The harmonic
oscillator is too simple for this as the phase-space speed in entirely uniform. The continuity equation for
f(q,p,ζ) shows directly that rather than speed it is strain
rate, (δ饗/δ饙) = (−f/r) that is crucial to the equivalence
between time scaling and probability density. To clarify
this point we consider the Quartic oscillator, with H_Q =
\( (q^4/4) + (p^2/2) \).

V.3. The Phase-Space Strain Rate
of the Quartic Oscillator

The equilibrium one-dimensional quartic oscillator,
\{q̇ = p; ṗ = −q^3\}, obeys Liouville’s Theorem,
\( \dot{f}/\dot{f} = −(δq/δq) = −(\partial q/\partial q) − (\partial p/\partial p) = −0 − 0 = 0 \).
One might expect then that all the accessible oscillator states
are equally likely, traversed at equal speeds. But they are not.
The speed, with initial conditions \((q,p) = (0,1)\) varies be-
tween 1 and 2\(3/4 = 1.6818\). The oscillator conserves its en-
ergy so that its trajectory is just a one-dimensional line in
(q,p) space, with a varying speed. To the left in Fig. 6 we
see the oscillator (q,p) trajectory and the time-dependence
of the speed in phase space, \( \sqrt{p^2 + q^6} \). To the right we see
the strain rate of the one-dimensional trajectory with ini-
tial condition (q,p) = (0,1). This is calculated two ways:
(1) the strain-rate parallel to the trajectory, \( (r \cdot v)/(r \cdot r) \);
(2) the largest local Lyapunov exponent, calculated by con-
sidering the constraint required to maintain the length of an
infinitesimal vector \( (δ_q, δ_p) \) tied to the (q,p) trajectory:
\( \{q̇ = p; ṗ = −q^3\} \rightarrow \{δ̇_q = δ_p − λ δ_q; δ̇_p = −3q^2 δ_q − λ δ_p \} \rightarrow \lambda = δ_q δ_p (1 − 3q^2) \).

Because the motion is regular and periodic there can be no
exponential growth of small perturbations. But the local val-
ues of the Lyapunov exponent vary in the range [−1 to +1].
This example shows forcefully that Liouville’s Theorem is misleading when applied to a single-system trajectory. In the one-dimensional case, with only two phase-space directions, the longitudinal and transverse strains exactly cancel, Liouville’s Theorem. The transverse strain rate, eliminated by energy conservation is equal to the second Lyapunov exponent. The first, plotted to the right in Fig. 6, gives the local logarithmic rate of longitudinal expansion of an infinitesimal element of length as a function of time. As the motion is periodic the mean value of both exponents is zero. The analogous details for a one-dimensional harmonic oscillator’s elliptical phase-space orbit have been published in Ref. [30].

VI. AN APPARENT NOSÉ-HOOVER-DETTMANN PARADOX

In all there are three separate routes to exactly the same outcome, the Nosé-Hoover oscillator motion equations and their stationary probability density:

\[ f(q, p, ζ) = s(q, p, ζ) = e^{-(q^2 + p^2 + ζ^2)/2} ; \]

1. Nosé’s Hamiltonian [3, 4], followed by time-scaling (multiplying all rates by \( s \)).
2. Hoover’s continuity-equation derivation [5, 6]:
   \[ (-\dot{f}/f) = (\partial q/\partial q) + (\partial p/\partial p) + (\partial ζ/\partial ζ) . \]
3. Dettmann’s Hamiltonian [7, 9], set equal to zero and equivalent to setting Nosé’s to zero.

Hoover’s derivation has the simplest assumptions, depending only on the continuity of the variables \((q, p, ζ, f)\), separability, and linearity. That is, assume that \( f(q, p, ζ) \) is separable, and of course positive, and that \( ζ \) has the simplest possible (linear) effect on the trajectory. The consequence is a differential equation for the functional dependence of the linear friction coefficient \( ζ \) on the oscillator variable \( p \):

\[ \{ \dot{q} = p ; \dot{p} = -q - ζp \} ; f = e^{-(q^2 + p^2)/2} e^{ζ(ζ)} ; \]

\( (\partial \ln f/\partial t) = 0 = \dot{q} + \dot{p} - ζ(\partial g/\partial ζ) - (\partial p/\partial p) = \)

\[ = -ζp^2 - ζ(\partial g/\partial ζ) + ζ \rightarrow \]

\[ \{ g = -(ζ^2/2) ; ζ = p^2 - 1 \} . \]

Alternatively, if the frictional force is cubic, \( \dot{p} = -q - ζp^3 \), we again find the Gaussian solution:

\[ 0 = -ζp^4 - (p^4 - 3p^2)(-ζ) + 3ζp^2 \leftarrow \]

\[ \{ g = -(ζ^2/2) ; ζ = p^4 - 3p^2 \} . \]

This alternative suggests that other odd powers of \( p \) or other even integrable functions of \( ζ \) could be used in its probability density, as is indeed the case [14–16].

Let us next consider the difference between two descriptions of a thermostated oscillator – the one a one-dimensional trajectory in a three or four-dimensional phase space; the other a three- or four-dimensional flow of an ensemble of systems living in the same phase space. We will focus on the surprising qualitative differences among the three- and four-dimensional flows described by Nosé, Dettmann, and Nosé-Hoover dynamics. All of them, even three-dimensional Nosé-Hoover, can be analyzed in a four-dimensional \((q, p, s, ζ)\) phase space, or in a three-dimensional subspace corresponding to the single-trajectory restriction of constant energy. To promote the Nosé-Hoover flow to four dimensions it is only necessary to define \( s \equiv sζ \).

Liouville’s Theorem then can apply to all three sets of equations. The Theorem establishes that the four-dimensional Hamiltonian probability density flows like an incompressible fluid, with \( f \equiv 0 \), just as in the familiar two-dimensional case:

\[ \{ \dot{q} = (\partial H/\partial p) ; \dot{p} = - (\partial H/\partial q) \} \rightarrow \]

\[ f = (\partial f/\partial t) + \sum \dot{q}(\partial f/\partial q) + \dot{p}(\partial f/\partial p) = 0 . \]

The Nosé \((s^0)\) and Dettmann \((s^1)\) oscillator Hamiltonians differ by just a factor \( s \):

\[ H_{N,D} = (s^{0.1}/2)[q^2 + (p/s)^2 + \ln(s^2) + ζ^2] \equiv 0 ; ζ \equiv ps . \]

In both cases the resulting constant-energy dynamics develop in a three-dimensional constrained phase space. For instance we can choose a space described by the coordinate \( q \), scaled momentum \((p/s)\), and friction coefficient \( ζ \). With the energy fixed any one of the four variables \((q, p, s, ζ)\) can be determined from a convenient form of the constraint conditions:

\[ s = e^{-(1/2)[q^2 + (p/s)^2 + ζ^2]} \quad [\text{Dettmann and Nosé}] . \]

It is convenient to specify \((q, p/s, ζ)\) and then to select \( s \) to satisfy the \( H \equiv 0 \) constraints. A consequence of the Dettmann multiplier \( s^1 \) is the simple relationship linking solutions of the Nosé and Dettmann Hamiltonians:

\[ (q, p/s, ζ)_{\text{Dettmann}} \equiv s(q, p/s, ζ)_{\text{Nosé}} . \]
VI. 1. An Expanding Model in Four Dimensions

Nosé’s Hamiltonian, \( H_N = (1/2)[q^2 + (p/s)^2 + \ln(s^2) + \zeta^2] \), followed by the time-scaling, \((\dot{q}, \dot{p}, \dot{s}, \dot{\zeta}) \rightarrow (\dot{s}q, \dot{s}p, \dot{s}s, \dot{s}\zeta)\), leads to four equations of motion in \((q, p, s, \zeta)\) space:

\[
\begin{align*}
\dot{q} &= (p/s) ; \quad \dot{p} = -sq ; \quad \dot{s} = s\zeta ; \quad \dot{\zeta} = [(p/s)^2 - 1] \\
(\partial\dot{s}/\partial s) &= +\zeta \quad \text{[Dettmann]}. \end{align*}
\]

Exactly these same motion equations follow more simply from Dettmann’s Hamiltonian, with no need of time scaling. Because our initial condition has a higher “temperature”, \((p/s)^2 = 2.4025\), than the target of unity the short-time friction coefficient \(\zeta\) becomes positive. This suggests, from \(\dot{s} = s\zeta\), that Nosé’s (or Dettmann’s) oscillator’s phase volume begins by expanding rather than contracting. This expansion with a positive friction seems counter to Liouville’s Theorem, and suggests a paradox. Fig. 7 shows the details of this four-dimensional problem. The time scaling factor \(s\) is precisely equal to Gibbs’ canonical probability density.

With the short-time positive friction, \(\zeta > 0\), the flow does not contract rather than expand, despite the \(\hat{s}\) equation. Let us investigate this intriguing problem further.

VI. 2. An Incompressible Model?

Dettmann’s Hamiltonian, \( H_D = (s/2)[q^2 + (p/s)^2 + \ln(s^2) + \zeta^2] \), with the constraint \(H_D = 0\) imposed in the initial conditions, is not really incompressible:

\[
\begin{align*}
\dot{q} &= p/s ; \quad \dot{p} = -sq ; \quad \dot{s} = s\zeta ; \\
\dot{\zeta} &= -(1/2)[q^2 - (p/s)^2 + \ln(s^2) + \zeta^2] - 1 \\
(\partial\dot{s}/\partial s) + (\partial\dot{\zeta}/\partial p) &= +\zeta - \zeta = 0 \quad \text{[Incompressible?]}.
\end{align*}
\]

The flow equations certainly maintain a comoving four-dimensional hypervolume unchanged in size. This is nothing more than the usual application of Liouville’s Theorem and is no surprise. But taking the zero energy constraint into account reduces the flow to three phase-space dimensions, just as in the Nosé-Hoover picture. Let us look at that picture next. The quantitative details of the evolving phase probability are shown in Fig. 7.

VI. 3. A Contracting Model in Three Dimensions

Here either Nosé-Hoover dynamics or a three-dimensional version of Dettmann’s Hamiltonian, including the constant-energy constraint, gives the same results. A time-reversible frictional force, \(-\zeta p\), provides a steady-state Gaussian phase-space distribution \(e^{-[q^2 + (p/s)^2 + \zeta^2]/2}\). In the two versions of dynamics the friction coefficient \(\zeta\) is determined by the feedback integral of temperature fluctuations around the target of unity:

\[
\begin{align*}
\{\dot{q} = p ; \quad \dot{p} = -q - \zeta p ; \quad \dot{\zeta} = p^2 - 1\} &\rightarrow \\
(\partial\dot{p}/\partial p) &= -\zeta \quad \text{[Nosé – Hoover]}. \\
\]

Dettmann’s motion equations are identical to these if his scaled momentum \((p/s)\) is replaced by the symbol \(p\):

\[
\begin{align*}
\{\dot{q} = (p/s) ; \quad \dot{p} = -qs ; \quad \dot{s} = s\zeta\} &\rightarrow \\
\{\dot{q} = p ; \quad \dot{p} = -q - \zeta p ; \quad \dot{s} = s\zeta\}.
\end{align*}
\]

Here, with the relatively “hot” initial condition, the three-dimensional phase-space volume shrinks (correctly) initially due to contraction parallel to the momentum axis. So, for the three phase-space descriptions of the same physical problem we have found expansion, incompressibility, and compression, all for exactly the same phase-space states. We put these three examples forward from the standpoint of pedagogy, as a useful and memorable introduction to the significance of Liouville’s Theorem for Dettmann’s constraint, \(H_D = 0\). But the early-time association of increasing phase volume, expected from \((\partial\dot{s}/\partial s) = \zeta > 0\), is indeed paradoxical.
Let us define the integration “error” for a $dt$ step as the rms difference between the coarser $dt$ solution and the finer solution with two successive steps of $dt/2$. To illustrate we consider Nosé’s original Hamiltonian approach applied to the harmonic oscillator:

$$\{ \dot{q} = p/s^2 ; \dot{p} = -q ; \dot{s} = \zeta ; \dot{\zeta} = (p^2/s^3) - (1/s) \} \text{[Nosé].}$$

The rms error here is $\sqrt{dq^2 + dp^2 + ds^2 + d\zeta^2}$.

With double precision arithmetic it is convenient to choose $dt$ such that the error for the oscillator lies between the values of $10^{-12}$ and $10^{-10}$. Whenever the error is too large, greater than $10^{-10}$, we cut the timestep in half; whenever the error is too small, less than $10^{-12}$, we double $dt$. Such an automated strategy is easily implemented and works quite well with “stiff” differential equations like Nosé’s or Sprott’s Signum oscillator [16, 17].

In Fig. 8 we show the range of timesteps that results from these motion equations. The integration error was constrained to lie between $10^{-10}$ and $10^{-12}$ for this demonstration. One million successful steps were taken. The minimum step $2^{-28}$ lay below the average, $2^{-9}$, by about 19 powers of 2. We show one quarter million steps in the figure.

VII. 2. Achieving Ergodicity with the 0532 Model

Gibbs’ ensembles include all phase-space states consistent with the independent thermodynamic variables, like energy, pressure, volume, and temperature. Particularly in small systems with just a few phase-space dimensions dynamical ergodicity, as in the case of the Signum thermostat of Fig. 4, is desirable. In 2015 it occurred to us that “weak control” could constitute a viable path to ergodicity. This led us to the “0532 Model”, a smooth and ergodic representation of Gibbs’ canonical distribution for the harmonic oscillator [31]:

$$\{ \dot{q} = p ; \dot{p} = -q - 0.05\zeta p - 0.32\zeta (p^3/T) ; \dot{\zeta} = 0.05[(p^2/T) - 1] + 0.32[(p^4/T^2) - 3(p^2/T)] \} \text{[0532 Model].}$$

Notice that the model includes a linear combination of second-moment and fourth-moment controls rather than one or the other of these possibilities. There are many other combinations which lead to ergodic dynamics. For more details see Ref. [31]. The nullclines for the equilibrium model, where $T = 1$, are near $p = \pm 1.7$ where $\dot{p}$ vanishes. Otherwise the $p(q)$ section for the 0532 model looks much like Signum case of Fig. 4. Time and mirror symmetry for the model imply fourfold symmetry in the Sections just as in the examples of Figs. 3 and 4. Both of these symmetries disappear in the nonequilibrium case that the temperature becomes a function of coordinate, the dynamics becomes dissipative, and the phase-space distribution becomes fractal, all of which we illustrate next. The mirror symmetry is destroyed by the temperature gradient while the time symmetry

VII. SOLVING DIFFERENTIAL EQUATIONS-QUANTIFYING ERGODICITY

Mechanical simulations require solving differential equations and analyzing the results. Solutions are necessarily numerical, almost always in the form of time series, and often produced by packaged software. Creating one’s own software is both a pleasure and an insurance policy, guarding against inflexible programming which is hard to understand or improve. Once the underlying model has been reduced to differential equations and once these have been “solved”, represented by a time series of salient variables (coordinates, momenta, energies, ...), analysis takes over. Once again it is simplest to maintain a personal working library of transparent software for creating, displaying, and analyzing data files. In our own work there is a recurring need for the analysis of dynamical instability, “Lyapunov instability”, which causes small errors to grow, exponentially fast, as $e^{\lambda(t)}$. Let us consider numerical simulation work in more detail, beginning with solving the equations and continuing with the analysis of the resulting data.

VII. 1. Integration of Ordinary Differential Equations

Although there is an extensive literature describing “symplectic” finite-difference schemes for solving the molecular dynamics problems, much of it available on the arXiv, there is no real need for these schemes in the research work we enjoy [17]. In our experience fourth-order Runge-Kutta integrators, where the programming is both simple and transparent, are best. Because integration errors vary as $dt^4$ over a fixed (sufficiently short) time interval, these can readily be estimated by comparing the result of a single timestep $dt$, to the result of two timesteps of half the length ($dt/2$).
is destroyed by irreversibility, which allows for the dissipative solutions that satisfy the Second Law of Thermodynamics, but steadfastly prevents their reversal. See Fig. 9 and note that both symmetries, $\pm q$ and $\pm p$ have disappeared.

**VIII. NONEQUILIBRIUM DIFFERENTIAL EQUATIONS AND MAPS**

![Image of the 0532 model strange attractor](image_url)

**Fig. 9.** Three cross-sections of the 0532 model strange attractor with maximum temperature gradient of 0.5. Each of the variables is shown in the range $-5 < q,p,\zeta < +5$. The two nonzero Lyapunov exponents for this system are $0.1135$ and $-0.1445$, producing a “strange attractor”. The Kaplan-Yorke dimension of this fractal is $2 + (0.1135/0.1445) = 2.785$, a zero-volume object in the three-dimensional ($q, p, \zeta$) space.

Letting the temperature vary smoothly in the cold-to-hot range from 0.5 to 1.5 provides a simple instructive three-dimensional nonequilibrium flow problem with a maximum temperature gradient of 0.5:

$$0.5 < T(q) \equiv 1 + 0.5 \tanh(q) < 1.5 \rightarrow (dT/dq)_{q=0} = 0.5.$$

Although the mass current $\langle p \rangle$ necessarily vanishes, the heat current $Q = \langle p^2/2 \rangle$ does not. Heat flows primarily from hot to cold and is responsible for the dissipation which causes the collapse of phase volume,

$$\dot{p} = -0.05 \zeta p - 0.32 \zeta(p^3/T) \text{ [0532 Model]} \rightarrow -\left(\dot{S}/k\right) = \langle(\dot{\zeta})/\zeta\rangle = \langle\partial\dot{p}/\partial p\rangle =$$

$$= \langle -0.05\zeta - 0.96\zeta(p^3/T) = (Q/kT) \rangle = -0.0310.$$

This relatively simple example of a stationary nonequilibrium flow helps convey three lessons, treated in what follows: (1) Lyapunov instability, the exponential growth of small perturbations. This is the main mechanism for the mixing of states; we will describe how to characterize it. (2) The formation of strange attractors, with at least one positive Lyapunov exponent but with a negative overall sum, is the typical situation away from equilibrium. The irreversible attractors provide the microscopic analog of the macroscopic Second Law of Thermodynamics. The simplest relevant example we know of is the time-reversible compressible Baker-Map Model [32–35]. (3) The fractal dimension of strange attractors can be related to Lyapunov instability through the balance of chaotic growth with dissipative decay. We consider these three lessons in turn, beginning with a look at Lyapunov’s ideas from a bit over 100 years ago.

**VIII. 1. Lyapunov Instability**

Alexander Lyapunov (1857–1918) characterized the (exponential) instability of differential equations in terms of the growth and decay exponents describing the deformation of a phase space hypersphere. An $N$-dimensional problem with $N$ ordinary differential equations, is characterized by $N$ exponents. Their sum gives the change of phase volume, $\sum \lambda = (\dot{\zeta}/\zeta)$, zero at equilibrium and negative for nonequilibrium steady states, corresponding to the formation of a strange attractor.

The simplest nonequilibrium flow problems are three-dimensional, the minimum for chaos. They can be described by three exponents, $\{\lambda\}$ with the first and largest easy to calculate, the second equal to zero, and the third negative, large enough to provide the negative sum, $\lambda_1 + \lambda_3 < 0$ consistent with the Second Law of Thermodynamics. The first and largest exponent, $\lambda_1 = \langle \lambda_1(t) \rangle$, can be determined by measuring the growth rate of small perturbations. In practice this is done by following two neighboring solutions (a “reference” and its “satellite”) and evaluating their short-term tendency to separate. At the end of each timestep the separation $\delta$ is compared to the target value $\delta_0$, (typically $10^{-5}$ or $10^{-6}$). The rescaling operation necessary to return the separation to the target value defines the local exponent $\lambda_1(t)$:

$$\langle q,p,\zeta \rangle_s = \langle q, p, \zeta \rangle_r + (\delta_0/|\delta|) \delta;$$

$$\delta \equiv [(q, p, \zeta)_s - (q, p, \zeta)_r] ; \lambda_1(t) \equiv -\ln(|\delta|/\delta_0)/dt.$$

The third (negative) exponent gives the overall negative sum, $\lambda_1 + 0 + \lambda_3 < 0$, required for convergence of the phase-space distribution. A straightforward method for finding $\lambda_3$ when the equations are time-reversible, is to store and reverse a forward trajectory [36]. When analyzed backward (again keeping a satellite trajectory close to the reversed reference) the largest Lyapunov exponent is $-\lambda_3$ and the negative exponent is $-\lambda_1$. The reversed trajectory, the “repellor”, acts as a source for the phase-space flow, from the repellor to the attractor.

In order better to understand the strange attractors we describe and illustrate a two-dimensional map. This map conveys the same lessons as a three-dimensional flow, or a many-body dissipative simulation, but in the simplest setting possible. The two-dimensional map can be pictured as relating two successive cross-sections of a three-dimensional flow.

**VIII. 2. The Nonequilibrium Time-Reversible Compressible Baker Map**

The “Baker Map” name recalls the physical mixing implemented by kneading dough. This pedagogical nonequilibrium map [32–35] “N” allows for the variable compression of the dough, leading to a “fractal” (fractional-dimensional)
Thus a small one-dimensional line exposed to the map—
either a tiny two-dimensional area shrinks as thought to be exact in this case, relating fractal structure to Lyapunov instability, the third nonequilibrium lesson we’ll relate to the Baker Map and conducting oscillator models.

VIII. 4. Fractal Dimensionality

Dimensionality is simply related to scaling relationships. A three-dimensional cube doubled in size contains eight times the mass. A square four times and a line two times. The same idea can be applied to fractional noninteger ideas about dimensionality. If a steady-state structure in phase space has growth and decay rates of $+0.1135$ and $-0.1445$ respectively the area covered varies as $e^{-0.0.031034}$ while the length varies as $e^{0.113504}$. Characterizing ergodicity in a three-dimensional problem can be addressed by sectioning the phase space in a search for (nonergodic) “holes”. See again the $(q, p)$ sections of Fig. 3.

Despite the additional complexity of the rotated coordinate system the $(q, p)$ version has the physical advantage of time reversibility and the computational advantage of irrational numbers in the mapping, which substantially delay the formation of periodic orbits.

The information dimension $D_I$ is the limiting small-mesh ratio $\langle \ln(p) \rangle / \ln(\delta)$ where $p$ is the probability associated with an element of the mesh and $\delta$ is the mesh size. Evidently a $D$-dimensional object of unit volume would have mesh element probabilities of $\delta^D$ and the resulting average would agree with the ordinary notion of (integer) dimensionality. To analyze the Baker Map the simplest approach is to store a reasonable number of $(x, y)$ points, $2 \times 10^{11}$ rotated $(q, p)$ points, reduced to lie within the unit square. For illustrative purposes we use two hundred billion successive $(x, y)$ points. This takes a few hours’ effort on a typical laptop computer. The information dimension was conjectured by Kaplan and Yorke to agree with a linear interpolation to zero strain rate between the last positive Lyapunov sum (starting with the largest value) and the first negative sum. For the Baker Map in two dimensions this gives the estimate:

$$D_I \equiv D_{KY} = 1 - (\lambda_1/\lambda_2) = 1 + \ln(27/4)/\ln(27/2) = 1.733680.$$
Although the Kaplan-Yorke conjecture is plausible (estimating the blend of expansion and contraction which gives a vanishing strain rate) and has been proved true [32, 33] for a wide variety of maps, there are examples in which it definitely appears to fail [37]. The pedagogical simplicity of the Map suggests it as a canonical analog of nonequilibrium simulations, fit for numerical and theoretical exploration. A plausible statistical model follows from the observation (easily verified numerically) that two-thirds of the Map iterations give compression in the y direction and one-third give expansion. This Map is therefore equivalent to a one-dimensional random walk with a variable step length. Choosing a random number $R$ for each iteration the stochastic model we use (for $0 < y < 1$) is:

$$ R < 2/3 \rightarrow y = y/3; \quad R > 2/3 \rightarrow y = (1 + 2y)/3. $$

The information dimension for as many as a trillion iterations of the FORTRAN Random Number routine can then be analyzed using a mesh length $(1/3)^n$ for $n$ as large as 19. A plot of some easily accessible results, $D_I$ as a function of $-1/\ln(\delta)$, provides a nice straight line, as shown in Fig. 11. An apparent fly in the Kaplan-Yorke ointment can be seen by looking at the Kaplan-Yorke estimate as $\delta$ approaches zero. $D_{KY} \approx 0.7337$ while our numerical estimate from data is $0.7415 \pm 0.001$. Thomas Gilbert pointed out to us that the convergence of the information-dimension calculation can be nonuniform. In the fine-mesh limit both the number of iterations and the number of bins must be large. He suggested that a different mesh, $\delta = 2^{-n}$ rather than $\delta = 3^{-n}$ might give quite different results. We found this to be true, making computational determinations of the information dimension somewhat problematic for nonlinear problems.

Our numerical random-walk results for $D_I$ conform to theory, agreeing with the $(q,p)$ mapping “information dimensions” for feasible values of $\delta$. Despite this agreement it is true that the nonuniform convergence of the limiting process means that the extrapolation of Fig. 11 is incorrect!

$$ D_I \equiv 1 + \sum_i p_i \ln(p_i)/\ln(1/\delta) \quad \text{[one dimension]}. $$

Such determinations are much more economical than their two-dimensional twins:

$$ D_I \equiv \sum_{i,j} p_{i,j} \ln(p_{i,j})/\ln(1/\delta) \quad \text{[two dimensions]}. $$

Our detailed investigation of this Baker Map dimensionality took us a few days and is still under investigation. Evidently this project was well worthwhile. The results so far suggest compressible Baker Map estimates from the statistical model agree with those using two-dimensional meshes. It was a surprise to find that the limiting $\delta \to 0 D_I$ given correctly by Kaplan-Yorke is prone to error when pursued by systematic extrapolation. Further unpublished results with trillions of iterations and $n = 19$ are fully consistent with the figure. We expect to report more details on this interesting feature of the compressible Baker Map.

**Fig. 11. Variation of the apparent information dimension of the unit-square Baker Map with the mesh size \( \{3^{-n}\} \), with \( 4 < n < 17 \) and \( 2 \times 10^{12} \) iterations of the \((q,p)\) map analyzed in the unit \((x,y)\) square. The random-walk model, with compressive steps for \( 0 < R < 2/3 \) and expanding steps for \( 2/3 < R < 1 \), and the complete two-dimensional mapping are compared with the red and black points. The two approaches are consistent with each other to five figures and suggested incorrectly that the Kaplan-Yorke information dimension (blue) was incorrect. The dependence of the apparent value of $D_I$ on the choice of mesh was a surprise and deserves more attention.**

**IX. IRREVERSIBILITY AND THE SECOND LAW OF THERMODYNAMICS**

The agreement of the linear interpolation and stochastic models to the deterministic time-reversible Baker Map provides an intuitive understanding of the Second Law of Thermodynamics [25]. In the general case of a thermostated time-reversible nonequilibrium steady state the long-time-averaged flow from a zero-probability fractal repellor to its mirror-image zero-volume strange attractor is invariably “dissipative”. Microscopic dissipation is characterized by phase-volume shrinking, $\otimes \to 0$ as the macroscopic dissipative heat is generated by the flow and extracted by time-reversible “thermostated” motion equations.

It is because the repellor has a positive Lyapunov sum, corresponding to an (impossible) exponential divergence of the phase volume, $\otimes \to \infty$, that repellor states can only arise by storing and reversing a dissipative trajectory. With digital computers any stationary state simulation will eventually generate a periodic orbit [38]. Using single-precision arithmetic the Baker Map generates a periodic orbit of reasonable
length. With double precision the length of the period is inaccessible to an informal investigation.

We believe that the most valuable result catalyzed by Nosé’s exploration of computational thermostats is the understanding of the inevitable statistical favoring of flows obeying the Second Law (that nonequilibrium flows are dissipative). Likewise one can simply look and see that nonequilibrium states are of vanishing probability relative to Gibbs’ equilibrium states. The fascinating fractal character of nonequilibrium states underlines the interest in the topological study of phase-space structure. One can imagine a continuous probability distribution becoming fractal. This picture seems entirely unlike the one-dimensional trajectory pursued by an individual nonequilibrium system in its point-by-point exploration of $6N$-dimensional floating-point phase space. Whether or not the distinction between (1) continuous variables and (2) the digital ones we use in modeling them is significant could use a transparent investigation from a kind-hearted mathematician, assuming his existence!

X. FUTURE CHARACTERIZATIONS OF DYNAMICAL SYSTEMS

The oscillator, Galton Board, and Baker Map problems provide an excellent introduction to nonlinear dynamics, chaos, and, by venturing into the many nonequilibrium applications of the thermostat idea, fractal geometry. A particularly simple nonequilibrium model is the one-dimensional $\phi^4$ chain, where each particle interacts with a harmonic nearest-neighbor force and is also tethered to its lattice site by a quartic potential. Adding thermostat forces to both ends of the chain results in a conductive heat current from the “hot” end to the “cold” one and invariably provides a fractal (fractional-dimensional) phase-space attractor [39]. See again Fig. 9 for the oscillator version of such a fractal.

The generic properties of the compressible Baker Map [Lyapunov instability, steady-state irreversible flow from a zero-volume ergodic fractal repeller to a mirror-image strange attractor, quadratic dependence of the dissipation rate, $(\dot{c}/c)$, on the deviation from equilibrium] provide a fine illustration of the macroscopic Second Law of Thermodynamics in terms of a microscopic time-reversible deterministic thermomechanics. At the same time the fractal nature of the strange attractor-repellor pair still contains mysteries appropriate to more computational research. Mathematics seems to be of little help here. The very notion of an attractor in mathematics seems qualitatively unlike our computational observations.

In mathematics an attractor is thought of as an “infinite” set of points, but with the concept of infinity muddled by the undecidability of the continuum hypothesis. The concept of the cardinal number $\aleph_0$, as the number of integers, or rationals, is not at all controversial. That a “continuum” is different is obvious so that a count of points “in” the continuum introduces a new infinity, sometimes called $c$. Gödel is credited with showing that it can’t be shown whether or not $c$ and $\aleph_1 = 2^{\aleph_0}$ are one and the same. This standstill has lasted nearly a century. At the moment the validity of the continuum hypothesis looks suspiciously like a “meaningless question”, divorced from the reality of computation.

From the computational standpoint it appears that our floating-point numbers, all of them rational, are certainly not a continuum. But they represent it well. Even quadruple-precision arithmetic (closer to the continuum?) is tedious in practice and typically teaches us nothing new. From the computational standpoint the number of points in a two-dimensional array can be arbitrarily larger than the number of those in a one-dimensional array. Likewise for three dimensions relative to two. In mathematics whether the continuum is one-, two-, or three-dimensional the “number of points” $c$ is all the same. It is here that mathematics seems to deviate from useful to useless.

The computational analysis of fractals introduces a non-integral dimension missing from mathematics. In the vicinity of a point within a fractal one can characterize the density of nearby points with a power law, $\delta^D$. $D$ can be nonintegral—the existence of the power law can vary wildly with direction and can be made more precise and detailed by increasing the precision or decreasing the mesh size to the limit of one’s budget. Example problems shedding more light on the microstructure of nonequilibrium fractals remain a pressing need.

Acknowledgment

We specially thank Thomas Gilbert for pointing out that the apparent information dimension of the data in Fig. 11, $D_I \to 0.741$, is incorrect and that a different choice of mesh, $\delta = 2^{-n}$, gives yet another incorrect apparent dimension. For more details see our arXiv Report 1909.04526, “Random Walk Equivalence to the Compressible Baker Map and the Kaplan-Yorke Approximation to Its Information Dimension”. We specially appreciate Gilbert’s preparation of an unpublished Note detailing the statistical analysis of the compressible dissipative Baker Maps. Thomas, together with Carl Dettmann, Ed Ott, Harald Posch, and James Yorke, also pointed us to the literature [32, 33] establishing that the Kaplan-Yorke conjecture has been proved true for linear Baker Maps of the type illustrated in Fig. 10 and 11.

References

William G. Hoover, Carol G. Hoover; Bill and Carol Hoover retired to Ruby Valley Nevada in 2005 where they built a home and continued their research work in computational physics, chaos, and nonequilibrium systems through the magic of the Internet. The air is clean, the weather mild, and the general ambience well-suited to contemplation and creativity. The Hoovers have published four books since moving to the valley with the most recent, Microscopic and Macroscopic Simulation Techniques published by World Scientific in 2018, a summing up of 11 two-hour lectures presented to graduate students at the Indian Institute of Technology at West Bengal pursuant to the invitation of their good friend, Professor Baidurya Bhattacharya.